

# **EVCB14N Series**Modbus Communication Module User Guide



EVCB14NITOS (0 TRIACS / pressure independent)
EVCB14NIT2S (2 TRIACS / pressure independent)
EVCB14NIT4S (4 TRIACS / pressure independent)
EVCB14NDT4S (4 TRIACS / pressure dependent)

**EVCB14NIT0SF** (0 TRIACS / pressure independent / with feedback) **EVCB14NIT4SF** (4 TRIACS / pressure independent / with feedback)







### Introduction

The EVCB14N Series Modbus Communication Module User Guide provides information for using Neptronic® communication feature. The controller uses Modbus communication protocol over serial line in the RTU mode and provides a Modbus network interface between client devices and Neptronic EVCB14N Series devices.

The EVCB14N Series Modbus Guide assumes that you are familiar with Modbus terminology.

The following are the requirements for Modbus:

- Data Model. The EVCB Modbus server data model uses only the Holding Registers table.
- Function Codes. The EVCB Modbus server supports a limited function codes subset comprising:
  - o Read Holding Registers (0x03)
  - Write Single Register (0x06)
  - Write Multiple Registers (0x10)
- Exception Responses. The EVCB Modbus server supports the following exception codes:
  - Illegal data address
  - o Illegal data value
  - Slave device busy
- Serial Line. The EVCB Modbus over serial line uses RTU transmission mode over a two-wire configuration RS485 (EIA/TIA-485 standard) physical layer.
  - The physical layer can use fixed baud rate selection or automatic baud rate detection (default) as per the Modbus Auto Baud Rate device menu item or holding register index 1.
  - The supported baud rates are 9600, 19200, 38400, and 57600.
  - The physical layer also supports variable parity control and stop bit configuration as per the Modbus Comport Config device menu item or holding register index 2.
  - In auto baud rate configuration, if the device detects only consecutive bad frames (2 or more) for one second with any given baud rate, it will reinitialize itself to the next baud rate.
- Addressing. The EVCB device only answers at the following address:
  - The device's unique address (1 to 246) that can be set through the device menu or through holding register index 0.



## **Holding Registers Table**

## **Table Glossary**

Name	Description	Name	Description
W	Writable Register	ASCII	For registers containing ASCII (8-bit) characters
RO	Read Only Register	MSB	Most Significant Byte
Unsigned	For range of values from 0 to 65,535, unless otherwise specified	LSB	Least Significant Byte
Signed	For range of values from -32,768 to 32,767, unless otherwise specified	MSW	Most Significant Word
Bit String	For registers with multiple values using bit mask (example, flags)	LSW	Least Significant Word

## **Holding Register Table**

Register Index	Description	Data Type	Range	Writable
4000 <b>0</b>	Modbus Address and Product Type.	Unsigned	MSB = Product type (e.g. 111 for EVCB) LSB = Modbus Address (e.g. 1-246)	W
40001	MSTP Baud Rate.	Unsigned Scale 100	0, 9600, 19200, 38400, or 57600 0 = Auto Baud Rate Detection Value/100 (e.g. 38400 baud = 384)	W
4000 <b>2</b>	Modbus Slave Communication Port Configuration.	Unsigned	1= No parity, 2 Stop bits 2= Even parity, 1 stop bit 3= Odd parity, 1 stop bit	W
4000 <b>3</b>	Product Name (characters 8 & 7).	ASCII	1 to 65,535 char 8: 0x53 = S char 7: 0x00 =	W
4000 <b>4</b>	Product Name (characters 6 & 5).	ASCII	1 to 65535 char 6: 0x49 = I char 5: 0x34 = 4	W
4000 <b>5</b>	Product Name (characters 4 & 3).	ASCII	1 to 65535 char 4: 0x42 = B char 3: 0x4E = N	W
4000 <b>6</b>	Product Name (characters 2 & 1).	ASCII	1 to 65535 char 2: 0x45 = E char 1: 0x56 = V	W





Register Index	Description	Data Type	Range	Writable
4000 <b>7</b>	Product actual firmware version.	Unsigned	1 to 65535 (e.g. 410)	RO
4000 <b>8</b>	Product actual EEPROM version.	Unsigned	1 to 65535 (e.g. 203)	RO
4000 <b>9</b>	System Status 1.	Bit String	[B0 – B11]: Reserved  B12: CO2 alarm  0 = Normal; 1 = Alarm  B13: Pressure mode (actual status)  0 = Independent; 1 = Dependent  B14: Air Flow  0 = Normal; 1 = Error	RO
400 <b>10</b>	System Status 2.	Bit String	[B0-B11, B13-B14]: Reserved <b>B12: Alarm override</b> 0 = Normal; 1 = Alarm	RO
400 <b>11</b>	Internal Temperature.	Unsigned Scale 100	0 to 5000 Value x 100 (e.g. 23°C = 2300)	RO
400 <b>12</b>	External Temperature.	Signed Scale 100	-4000 to 10000 Value x 100 (e.g. 18°C = 1800)	RO
400 <b>13</b>	Change Over Temperature.	Signed Scale 100	-4000 to 10000 Value x 100 (e.g. 18°C = 1800)	RO
400 <b>14</b>	Internal Humidity Internal humidity, reading of the integrated humidity sensor of TRLH or TRLGH. If not available the value will be fixed to 0x7FFF (32767)	Signed Scale 10	0 to 1000 Value x 10 (e.g. 45%RH = 450)	RO
400 <b>15</b>	Input 3 reading, pressure sensor value (*Not available on all models)	Unsigned	0 to 4000 mV	RO
400 <b>16</b>	Analog input 1 value.	Unsigned Scale 100	0 to 1000 Value x 100 (e.g. 2 mV = 200)	RO
400 <b>17</b>	Analog Input 2 value.	Unsigned Scale 100	0 to 1000 Value x 100 (e.g. 3 mV = 300)	RO





Register Index	Description	Data Type	Range	Writable
400 <b>18</b>	CO2 value in ppm If using TRLG or TRLG and CO2 is in TRL mode, it is the sensor value in ppm. If using Al1 or Al2 and CO2 is set in Analog more, the reading is from the external sensor.	Unsigned Scale 100	100 to reg 400 <b>98</b> <i>Value x 100 (e.g. 5 ppm = 500)</i>	RO
400 <b>19</b>	Air supply temperature.	Signed Scale 100	-4000 to 10000 Value x 100 (e.g. 5°C = 500)	RO
400 <b>20</b>	Control temperature.	Signed Scale 100	-4000 to 10000 Value x 100 (e.g. 25°C = 2500)	W
400 <b>21</b>	Heating demand for heating ramp 1.	Unsigned Scale 10	0 to 1000 Value x 10 (e.g. 25% = 250)	RO
400 <b>22</b>	Cooling demand for cooling ramp 1.	Unsigned Scale 10	0 to 1000 Value x 10 (e.g. 25% = 250)	RO
400 <b>23</b>	Temperature offset applied on internal temperature.	Signed Scale 100	-500 to 500 Value x 100 (e.g. 0.5°C = 50)	W
400 <b>24</b>	Temperature offset applied on external temperature.	Signed Scale 100	-500 to 500 Value x 100 (e.g. 0.5°C = 50)	W
400 <b>25</b>	Temperature setpoint used during the occupancy period of the day.	Unsigned Scale 10	Range: 400 <b>26</b> to 400 <b>27</b> <i>Value x 10 (e.g. 20°C = 200)</i>	W
400 <b>26</b>	Minimum temperature setpoint used during the day.	Unsigned Scale 10	Range: 100 to 400 <b>27</b> <i>Value x 10 (e.g. 10°C = 100)</i>	W
400 <b>27</b>	Maximum temperature setpoint used during the day.	Unsigned Scale 10	Range: 400 <b>26</b> to 400 <i>Value x 10 (e.g. 40°C = 400)</i>	W
400 <b>28</b>	Cooling setpoint during No Occupancy / Night Set Back	Unsigned Scale 10	Range: 400 <b>29</b> to 400 <i>Value x 10 (e.g. 22°C = 220)</i>	W
400 <b>29</b>	Heating setpoint during No Occupancy / Night Set Back	Unsigned Scale 10	Range: 100 to 400 <b>28</b> <i>Value x 10 (e.g. 16°C = 160)</i>	W
400 <b>30</b>	Cooling demand for proportional band 1.	Unsigned Scale 10	5 to 50 Value x 10 ( e.g. 0.3°C = 3)	W





Register Index	Description	Data Type	Range	Writable
400 <b>31</b>	Heating demand for proportional band 1.	Unsigned Scale 10	5 to 50 Value x 10 (e.g. 0.3°C = 3)	W
400 <b>32</b>	Cooling dead band for proportional band 1.	Unsigned Scale 10	0 to 50 Value x 10 (e.g. 0.3°C = 3)	W
400 <b>33</b>	Heating dead band for proportional band 1.	Unsigned Scale 10	0 to 50 Value x 10 (e.g. 0.3°C = 3)	W
400 <b>34</b>	Changeover temperature setpoint.	Unsigned Scale 10	100 to 400 Value x 10 (e.g. 12°C = 120)	W
400 <b>35</b>	Night setback override delay in minutes.	Unsigned	0 to 180 minutes	W
400 <b>36</b>	Integral time factor for heating in seconds.	Unsigned	0 to 250 seconds	W
400 <b>37</b>	Cooling anti-cycle delay: delay in minutes before activating or reactivating the cooling contact.	Unsigned	0 to 15 minutes	W
400 <b>38</b>	Floating time 1: Indicates the time in seconds required by the actuator to complete a 90° run.	Unsigned	15 to 250 seconds	W
400 <b>39</b>	Occupancy Delay Mode in minutes	Unsigned	0 to 180 minutes	W
400 <b>40</b>	Cooling demand for cooling ramp 2.	Unsigned Scale 10	0 to 1000 % Value x 10 (e.g. 30% = 300)	RO
400 <b>41</b>	Proportional band for cooling ramp 2	Unsigned Scale 10	5 to 50 Value x 10 (e.g. 0.2°C = 2)	W
400 <b>42</b>	Dead band for cooling ramp 2.	Unsigned Scale 10	0 to 50 Value x 10 (e.g. 0.2°C = 2)	W
400 <b>43</b>	Heating demand for heating ramp 2.	Unsigned Scale 10	0 to 1000 %  Value x 10 (e.g. 30% = 300)	W
400 <b>44</b>	Proportional band for heating ramp 2.	Unsigned Scale 10	5 to 50 Value x 10 (e.g. 0.2°C = 2)	W
400 <b>45</b>	Dead band for heating ramp 2.	Unsigned Scale 10	0 to 50 Value x 10 (e.g. 0.2°C = 2)	W



Not effective on all models.

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Register Index	Description	Data Type	Range	Writable
400 <b>46</b>	Changeover demand for the VAV box.	Unsigned Scale 10	0 to 1000 % Value x 10 (e.g. 30% = 300)	RO
400 <b>47</b>	Changeover proportional band: the range in which the controller modulates the cooling and heating output from 0 to 100%.	Unsigned Scale 10	5 to 50 Value x 10 (e.g. 0.2°C = 2)	W
400 <b>48</b>	Changeover deadband: the range at which the controller takes no action when the temperature is above or below the setpoint.	Unsigned Scale 10	0 to 50 Value x 10 (e.g. 0.2°C = 2)	W
400 <b>49</b>	AO1 min Vdc: minimum voltage of analog output 1.	Unsigned Scale 10	Range: 0 to reg. 400 <b>51</b> <i>Value x 10 (e.g. 2 Volts = 20)</i>	W
400 <b>50</b>	AO2 min Vdc: minimum voltage of analog output 2.	Unsigned Scale 10	Range: 0 to reg. 400 <b>52</b> <i>Value x 10 (e.g. 2 Volts = 20)</i>	W
400 <b>51</b>	AO1 max Vdc: maximum voltage of analog output 1.	Unsigned Scale 10	Range: reg. 400 <b>49</b> to 100 <i>Value x 10 (e.g. 10 Volts = 100)</i>	W
400 <b>52</b>	AO2 max Vdc: maximum voltage of analog output 2.	Unsigned Scale 10	Range: reg. 400 <b>50</b> to 100 <i>Value x 10 (e.g. 10 Volts = 100)</i>	W
	inimum and maximum voltages correspond to 0 to 100% demand. The reference applications, we recommend to leave the minimum voltage at 0		s always applied to the output. The maximum voltage is applied when the one when the demand is 0%.	demand reaches
400 <b>53</b>	Time of numerical filter of delta pressure in seconds.  Not effective on all models.	Unsigned	1 to 10 seconds	W
400 <b>54</b>	Factor of V=K*sqrt(dP), where dP = 1.  Not effective on all models.	Unsigned	Range: 100 to 9995 CFM	W
400 <b>55</b>	Minimum air flow for cooling.  Not effective on all models.	Unsigned	Range: 0 or (12.7%) Kfac to reg 400 <b>56</b> CFM	W
400 <b>56</b>	Maximum air flow for cooling.  Not effective on all models.	Unsigned	Range: reg 400 <b>55</b> to reg 400 <b>54</b> CFM	W
400 <b>57</b>	Minimum air flow for heating.  Not effective on all models.	Unsigned	Range: 0 or (12.7%) Kfac to reg 400 <b>58</b> CFM	W
400 <b>58</b>	Maximum air flow for heating.	Unsigned	Range: reg 400 <b>57</b> to reg 400 <b>54</b> CFM	W





Register Index	Description	Data Type	Range	Writable
400 <b>59</b>	Integral time factor of air flow in minutes.  Not effective on all models.	Unsigned	0 to 60 minutes	W
400 <b>60</b>	Actual air flow converted from delta pressure sensor.  Not effective on all models.	Unsigned	Range: 0 to reg 400 <b>54</b> CFM	RO
400 <b>61</b>	Air flow calculated from system demand.  Not effective on all models.	Unsigned	Range: 0 to 9999 CFM	RO
400 <b>62</b>	Configuration value for Air Flow Max used during airflow balancing sequence. Refer to EVCB-Airflow Balance Instructions.  Not effective on all models.	Unsigned	Range: 0 to 9999 CFM	W
400 <b>63</b>	Analog output 1 value.	Unsigned Scale 10	Unit: Volt, Range: reg 400 <b>49</b> to reg 400 <b>51</b> <i>Value x 10 (e.g. 5 Volts = 50)</i>	W
400 <b>64</b>	Analog output 2 value.	Unsigned Scale 10	Unit: Volt, Range: reg 400 <b>50</b> to reg 400 <b>52</b> <i>Value x 10 (e.g. 5 Volts = 50)</i>	W
400 <b>65</b>	Percentage of demand to close TRIAC output 1.  Not available on all models.	Unsigned	15 to 80%	W
400 <b>66</b>	Percentage of demand to close TRIAC output 2.  Not available on all models.	Unsigned	15 to 80%	W
400 <b>67</b>	Percentage of demand to close TRIAC output 3.  Not available on all models.	Unsigned	15 to 80%	W
400 <b>68</b>	Percentage of demand to close TRIAC output 4.  Not available on all models.	Unsigned	15 to 80%	W
400 <b>69</b>	Percentage of demand to open TRIAC output 1.  Not available on all models.	Unsigned	0 to reg 400 <b>65-</b> 4%	W
400 <b>70</b>	Percentage of demand to open TRIAC output 2.  Not available on all models.	Unsigned	0 to reg 400 <b>65</b> -4%	W
400 <b>71</b>	Percentage of demand to open TRIAC output 3.  Not available on all models.	Unsigned	0 to reg 400 <b>65-4</b> %	W
400 <b>72</b>	Percentage of demand to open TRIAC output 4.  Not available on all models.	Unsigned	0 to reg 400 <b>65-4</b> %	W



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Register Index	Description	Data Type	Rai	nge	Writable
400 <b>73</b>	Integral time factor for cooling in seconds.	Unsigned	0 to 250 seconds		W
400 <b>74</b>	Motor position. Not effective on all models.	Unsigned	0 to 100%		RO
400 <b>75</b> to 4	100 <b>80</b> - Reserved				RO
400 <b>81</b>	Air flow offset calibration. Refer to EVCB-Airflow Balance Instructions.Not effective on all models.	Signed	-500 to 500 CFM		W
400 <b>84</b>	Configuration value for Air Flow Min used during airflow balancing sequence. Refer to EVCB-Airflow Balance Instructions.  Not effective on all models.	Unsigned	Range: 0 to 9999 CFM		W
400 <b>82</b> , 40	40082, 40083, and 40085 to 40095 - Reserved				RO
400 <b>96</b>	Network fallback timeout Present Value in minutes.	Unsigned	0 to 60 minutes		W
400 <b>97</b>	Reserved				RO
400 <b>98</b>	Maximum range of the CO2 sensor connected to Al1 or Al2.	Unsigned	100 to 5000 PPM		W
400 <b>99</b>	Maximum concentration of CO2 before the EVC activates an alarm.	Unsigned	Range: 100 to the greater ppm value between 2000 and reg 40098		W
40 <b>100</b>	System Option 1.	Bit String	B3, B13-B14: Reserved  B0: Tstat temperature units  0 = Celsius; 1 = Fahrenheit  B1: Modbus temperature units  0 = Celsius; 1 = Fahrenheit  B2: Temperature setpoint lock  0 = Unlocked; 1 = Locked  B4: TO1/TO2 floating direction  0 = Direct; 1 = Reverse  B5: TO3/TO4 floating direction  0 = Direct; 1 = Reverse  B6: Onboard motor direction  0 = Direct; 1 = Reverse	B7: Freeze protection 0 = Disabled; 1 = Enabled  B8: User system off mode 0 = User can set Tstat to OFF 1 = User cannot set Tstat OFF  B9: Keypad bottom left lock 0 = Unlocked; 1 = Locked  B10:Keypad upper left lock 0 = Unlocked; 1 = Locked  B11: Keypad arrows lock 0 = Unlocked; 1 = Locked  B12: Program lock 0 = Unlocked; 1 = Locked  B15: Schedule 0 = Disabled; 1 = Enabled	W





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Register Index	Description	Data Type	R	ange	Writable
40 <b>101</b>	System Option 2.  Notes B14: Applies only if DI2 is in OverHeat or Override. B15: Configuration value of the fan operation when an output ramp is configured with the option "Fan On". When set to (0) On, the fan is continuously in operation even when EVC is off. When set to (1) Off, the fan turns off during the following conditions; User System Mode is set to OFF, when in night setback mode, scheduler forces the EVC OFF or when Digital Input 2 is set to Override and is active. <sup>(1)</sup> Not effective on all models.	Bit String	B0-B1, B13: Reserved  B2: Auto baud rate detection 0 = Enabled; 1 = Disabled  B3: Night setback mode 0 = Tstat ON; 1 = Tstat OFF  B4: A01 direction 0 = Direct; 1 = Reverse  B5: A02 direction 0 = Direct; 1 = Reverse  B6: T01 direction 0 = Direct; 1 = Reverse  B7: T02 direction 0 = Direct; 1 = Reverse	B8: TO3 direction <sup>®</sup> 0 = Direct; 1 = Reverse  B9: TO4 direction <sup>®</sup> 0 = Direct; 1 = Reverse  B10: Display RH <sup>®</sup> 0 = No; 1 = Yes  B11: Pressure mode select <sup>®</sup> 0 = independent; 1 = dependent  B12: Auto pressure mode <sup>®</sup> change 0 = Enabled; 1 = Disabled  B14: DI 2 Contact 0: NO; 1: NC  B15: Fan always "on" mode 0 = Always on; 1 = Follow NSB/NoOcc	W
40 <b>102</b>	Status value of the actual changeover control mode.	Unsigned	0 = Cooling , 1= Heating		RO
40 <b>103</b>	System command status. $^{\Phi}$ Not effective on all models.	Unsigned	0 = No Command, 1 = AirFlow 1	Balancing, 4 = AirFlow 2 Balancing	W
40 <b>104</b>	TO OnOff. * Not available on all models.	Unsigned	1 = TO1 OnOff 2 = TO2 OnOff	4 = TO3 OnOff 8 = TO4 OnOff	RO
40 <b>105</b>	Occupancy or night setback mode commands.	Unsigned	1 = Locally 2 = Off 3 = Occupancy	4 = NoOccupancy 5 = Day 6 = Night	W
40 <b>106</b>	Status of digital input 1.	Unsigned	0 = Open, 1 = Close		RO
40 <b>107</b>	Analog input 1 signal.  * Not available on all models.   Double The signal of the sign	Unsigned	1 = OFF 2 = ETS (external temp) 3 = SENS (changeover sensor) 4 = NoCL (normally cool) 5 = NoHT (normally heat)	6 = STFL* (setpnt airflow 0-10Vdc) 7 = CO2 (carbon dioxide) 8 = AST (air supply temp sensor) 9 = mor <sup>©</sup> (motor position)	W





Register Index	Description	Data Type	Range	Writable
40 <b>108</b>	User System Control Mode.	Unsigned	1 = AUTO 3 = COOL 2 = HEAT 4 = OFF	W
40 <b>109</b>	Sets the permissions or restrictions to change the system control mode by the user.	Unsigned	1 = AUTO $3 = COOL$ $2 = HEAT$ $5 = AUTO-LOCK$	W
40 <b>110</b>	Indicates the status of the Night Setback mode.	Unsigned	1 = Day, 2 = Night, 3 = Derogation	RO
40 <b>111</b>	Configuration of DI1 mode. Night setback or no occupancy status.	Unsigned	1=Off 4= Night Set Back NO 2= Occupancy NO 5= Night Set Back NC 3= Occupancy NC	W
40 <b>112</b>	Analog input 2 signal. *Not available on all models.	Unsigned	1 = OFF 2 = ETS (external temp) 3 = SENS (changeover sensor) 4 = NoCL (normally cool) 5 = NoHT (normally heat)  6 = STFL* (setpnt airflow 0-10Vdc) 7 = CO2 (carbon dioxide) 8 = AST (air supply temp sensor) 9 = mor (motor position)	W
40 <b>113</b>	Occupancy status of the zone.	Unsigned	1 = No Occupancy, 2 = Occupancy, 3 = Derogation	RO
40 <b>114</b>	AO1: Analog output 1 control ramp  Notes: Options 11 and 12 are for fan powered applications and only available with models: EVCB14NIT4S, EVCB14NDT4S, and EVCB14NIT4SF.  *Not available on all models.	Unsigned	1 = OFF6 = CO2 (carbon dioxide)2 = CR1 (cooling ramp 1)7 = STFL* (setpnt airflow 0-10Vdc)3 = CR2 (cooling ramp 2)8 - 10 = reserved4 = HR1 (heating ramp 1)11 = Fan Auto (follow demand)5 = HR2 (heating ramp 2)12 = Fan On (always on)	W
40115	AO2: Analog output 2 control ramp  Notes: Options 11 and 12 are for fan powered applications and only available with models: EVCB14NIT4S, EVCB14NDT4S, and EVCB14NIT4SF.  *Not available on all models.	Unsigned	1 = OFF 2 = CR1 (cooling ramp 1) 3 = CR2 (cooling ramp 2) 4 = HR1 (heating ramp 1) 5 = HR2 (heating ramp 2)  6 = CO2 (carbon dioxide) 7 = STFL* (setpnt airflow 0-10Vdc) 8 - 10 = reserved 11 = Fan Auto (follow demand) 12 = Fan On (always on)	W
40 <b>116</b>	TO1: Configuration of the ramp used to modulate (pulse or floating) or activate/deactivate (On/Off) TO1 based on demand.*  Not available on all models.	Unsigned	1 = OFF 2 = CR1 (cooling ramp 1) 3 = CR2 (cooling ramp 2) 4 = HR1 (heating ramp 1) 5 = HR2 (heating ramp 2)  1 = OFF 2 = CO2 (carbon dioxide) 7 = STFL* (setpnt airflow 0-10Vdc) 8 = COR* (changeover ramp) 9 = CH1* (cool/heat 1) 10 = ANLG* (analog 0-10Vdc) 11 = Fan Auto (follow demand) 12 = Fan On (always on)	W





Register Index	Description	Data Type		Range	Writable
40117	TO2: Configuration of the ramp used to modulate (pulse or floating) or activate/deactivate (On/Off) TO2 based on demand.*  Not available on all models.	Unsigned	1 = OFF 2 = CR1 (cooling ramp 1) 3 = CR2 (cooling ramp 2) 4 = HR1 (heating ramp 1) 5 = HR2 (heating ramp 2)	6 = CO2 (carbon dioxide) 7 = STFL* (setpnt airflow 0-10Vdc) 8 = COR* (changeover ramp) 9 = CH1* (cool/heat 1) 10 = ANLG* (analog 0-10Vdc) 11 = Fan Auto (follow demand) 12 = Fan On (always on)	W
40 <b>118</b>	TO3: Configuration of the ramp used to modulate (pulse or floating) or activate/deactivate (On/Off) TO3 based on demand.*  Not available on all models.	Unsigned	1 = OFF 2 = CR1 (cooling ramp 1) 3 = CR2 (cooling ramp 2) 4 = HR1 (heating ramp 1) 5 = HR2 (heating ramp 2)	6 = CO2 (carbon dioxide) 7 = STFL* (setpnt airflow 0-10Vdc) 8 = COR* (changeover ramp) 9 = CH1* (cool/heat 1) 10 = ANLG* (analog 0-10Vdc) 11 = Fan Auto (follow demand) 12 = Fan On (always on)	W
40 <b>119</b>	TO4: Configuration of the ramp used to modulate (pulse or floating) or activate/deactivate (On/Off) TO4 based on demand.*  Not available on all models.	Unsigned	1 = OFF 2 = CR1 (cooling ramp 1) 3 = CR2 (cooling ramp 2) 4 = HR1 (heating ramp 1) 5 = HR2 (heating ramp 2)	6 = CO2 (carbon dioxide) 7 = STFL* (setpnt airflow 0-10Vdc) 8 = COR* (changeover ramp) 9 = CH1* (cool/heat 1) 10 = ANLG* (analog 0-10Vdc) 11 = Fan Auto (follow demand) 12 = Fan On (always on)	W
40 <b>120</b>	TO1: Signal output type for TRIAC output 1.* Not available on all models.	Unsigned	3 = Pulsing, 4 = On_Off, 5 = Fl	oating	W
40 <b>121</b>	TO2: Signal output type for TRIAC output 2.*  Not available on all models.	Unsigned	3 = Pulsing, 4 = On_Off		W
40 <b>122</b>	TO3: Signal output type for TRIAC output 3.* Not available on all models.	Unsigned	3 = Pulsing, 4 = On_Off, 5 = Fl	oating	W
40 <b>123</b>	TO4: Signal output type for TRIAC output 4.* Not available on all models.	Unsigned	3 = Pulsing 4 = On_Off		W
40 <b>124</b>	Pressure independent output selection for VAV damper actuator.*  Not available on all models.	Unsigned	3 = Floating1, 4 = Floating2, 5	= Motor	W





Register Index	Description	Data Type	Range	Writable
40 <b>125</b>	Motor ramp: Configuration of the ramp used to modulate the actuator based on demand. *Not available on all models.	Unsigned	2 = CR1 (cooling ramp 1) 7 = STFL* (setpnt airflow 0-10Vdc) 3 = CR2 (cooling ramp 2) 8 = COR (changeover ramp) 4 = HR1 (heating ramp 1) 9 = CH1 (cool/heat 1) 5 = HR2 (heating ramp 2) 10 = ANLG (analog 0-10Vdc) 6 = Not Available	W
40 <b>126</b>	Changeover control mode status that indicates the source of changeover values.	Unsigned	1 = Local, 2 = Cooling, 3 = Heating	W
40 <b>127</b>	Reserved			RO
40 <b>128</b>	Reserved			RO
40 <b>129</b>	Configuration of DI2 mode.	Unsigned	1=Off 2=Override 3=OverHeat1  4=OverHeat2 5=OverHeatAll 5=ChangeOverNoCooling 7=ChangeOverNoHeating	W
40 <b>130</b>	Selected temperature control source (in Programming mode).	Unsigned	1 = Internal Temperature, 2 = External Temperature 3 = Remote Temperature	W
40 <b>131</b>	Airflow balance mode, enter the balancing mode to adjust air flow factor. <sup>©</sup> Not effective on all models.	Unsigned	1 = Close 3 = Maximum Flow 2 = Minimum Flow 4 = Full Open	W
40 <b>132</b>	Reserved			RO
40 <b>133</b>	Configuration to set the motor position in night setback mode. $^\Phi$ Not effective on all models.	Unsigned	1 = Auto 2 = Open	W
40 <b>134</b>	Digital input 2 delay in seconds.	Unsigned	0 to 3600 seconds	W
40 <b>135</b>	Time in seconds required by the actuator to complete a 90° run.*  Not available on all models.	Unsigned	15 to 250 seconds	W
40 <b>136</b>	Minimum motor position in percentage of stroke for cooling.*  Not available on all models.	Unsigned	0 to 100%	W
40 <b>137</b>	Minimum motor position in percentage of stroke for heating.*  Not available on all models.	Unsigned	0 to 100%	W
40 <b>138</b>	Airflow Hysteresis Stop in percentage.*Not available on all models.	Unsigned	1 to 100%	W
40 <b>139</b>	Airflow Hysteresis Start in percentage.*Not available on all models.	Unsigned	reg 40 <b>138</b> to 100%	W
40 <b>140</b>	Airflow scale.*Not available on all models.	Unsigned	1 = Scale1, 2 = Scale10, 3 = Scale100	W





Register Index	Description	Data Type	Range	Writable
40 <b>141</b>	Airflow fault deadband in percentage.*Not available on all models.	Unsigned	1 to 30%	W
40 <b>142</b>	Airflow fault error in percentage.*Not available on all models.	Unsigned	0 to 100%	W
40 <b>143</b>	Airflow fault hysteresis in percentage.*Not available on all models.	Unsigned	1 to 30%	W
40 <b>144</b>	Airflow fault time.*Not available on all models.	Unsigned	2 to 59 minutes	W
40 <b>145</b>	CL_HT SwitchTimer, waiting time before switching between the heating and cooling modes.	Unsigned	0 to 120 minutes	W
40 <b>146</b>	CL_HT SwitchTimerCount, countdown to indicate the swap between heating and cooling modes.	Unsigned	0 to 4,294,967,295 seconds	RO
40 <b>147</b>	FloatingTO1/TO2, TRIAC output 1 or 2 when set to floating, indicates the floating signal demand.*  Not available on all models.	Unsigned Scale 10	0 to 1000%  Value x 10 (e.g. 15% =150)	RO
40 <b>148</b>	FloatingTO3/TO4, TRIAC output 3 or 4 when set to floating, indicates the floating signal demand.*  Not available on all models.	Unsigned Scale 10	0 to 1000% Value x 10 (e.g. 15% =150)	RO
40 <b>149</b>	TO1 Pulsing, TRIAC output 1 when set to Pulsed, indicates the pulse signal demand. * Not available on all models.	Unsigned Scale 10	0 to 1000% Value x 10 (e.g. 15% =150)	RO
40 <b>150</b>	TO2 Pulsing, TRIAC output 2 when set to Pulsed, indicates the pulse signal demand. * Not available on all models.	Unsigned Scale 10	0 to 1000% Value x 10 (e.g. 15% =150)	RO
40 <b>151</b>	TO3 Pulsing, TRIAC output 3 when set to Pulsed, indicates the pulse signal demand.* Not available on all models.	Unsigned Scale 10	0 to 1000% Value x 10 (e.g. 15% =150)	RO
40 <b>152</b>	TO4 Pulsing, TRIAC output 4 when set to Pulsed, indicates the pulse signal demand.* Not available on all models.	Unsigned Scale 10	0 to 1000% Value x 10 (e.g. 15% =150)	RO
40 <b>153</b>	Over heat status.	Unsigned	1 = OverHeatNormal 3 = OverHeat2 2 = OverHeat1 4 = OverHeatAll	RO
40 <b>154</b>	Configuration to override the motor position.*  Not available on all models.	Unsigned	1 = Auto 2 = Open 3 = Close 4 = AirFlowCoolMin 5 = AirFlowCoolMax	W





Register Index	Description	Data Type	Range	Writable
40 <b>155</b>	Information displayed on the TRL.	Unsigned	1 = Temp Demand 2 = Setpoint Demand 3 = Temp  4 = Setpoint 5 = Off	W
40 <b>156</b>	Status of digital input 2.	Unsigned	0 = Open, 1 = Close	RO
40 <b>157</b>	Cfg_Input3 Minimum Reading, this setting represents the deadband of the pressure sensor in mV.* Not available on all models.	Unsigned	10 to 180 mV	W
40 <b>158</b>	System Options 3	Bit String	[B0-B1, B4-B6, B8, B10-B15]: Reserved  B2: CO <sub>2</sub> Display  0 = No; 1 = Yes  B3: CO <sub>2</sub> Control Source  0 = Analog; 1 = TRLG  B7: Occupancy Control Source  0 = B11; 1 = Intern Sensor  B9: Motor Position Control Temperature Fault  0 = Close; 1 = Open	W
40 <b>159</b>	System Options 4	Bit String	[B0 – B15]: Reserved	RO
40 <b>160</b>	Internal CO2, reading of the integrated CO2 sensor of TRLG or TRLGH. If not available the value will be fixed to 0x7FFF (32767)	Unsigned	0 to 2000 ppm	RO
40 <b>161</b>	Internal light sensor reading in Luxes.	Unsigned	0 to 16000 Luxes	RO
40 <b>162</b>	Internal VOC sensor reading in ppb.	Unsigned	1 to 60000 ppb	RO
40 <b>163</b>	Internal PIR sensor reading.	Unsigned	0 = NoOccupancy, 1 = Occupancy	RO
40 <b>164</b>	Occupancy minimum time in minutes.	Unsigned	0 to 240 minutes	W
40 <b>165</b>	Configuration value of the minimum position in cooling/heating mode in %.	Unsigned	0 to 100 %	W
40 <b>166</b>	Control SetPoint.	Unsigned Scale 1	10 to 40 Value x 1 (e.g. 30°C = 30)	RO

Notes			



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